

Simple views in polymer dynamics

APS symposium honoring P.G. de Gennes

SLIPPAGE

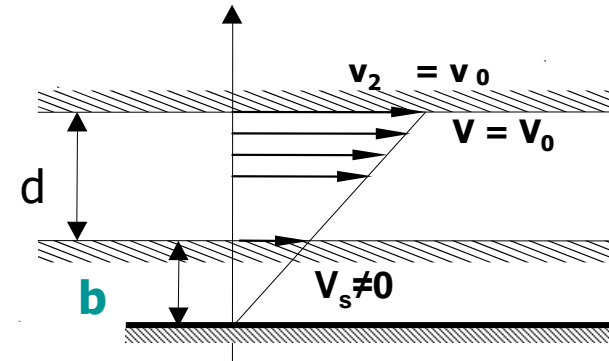
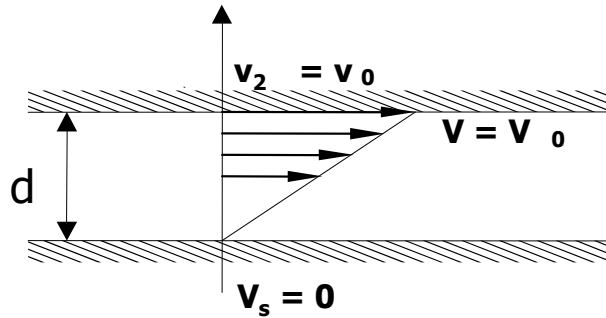


Liliane Léger

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Boundary condition for the velocity at the wall



Stress at interface:

$$\sigma = k_{FV} v_s = \eta \dot{\gamma}$$

$$\dot{\gamma} = \left. \frac{\partial v_x}{\partial z} \right|_{z=0} = \frac{v_s}{b}$$

Navier (1823)

Slip length b

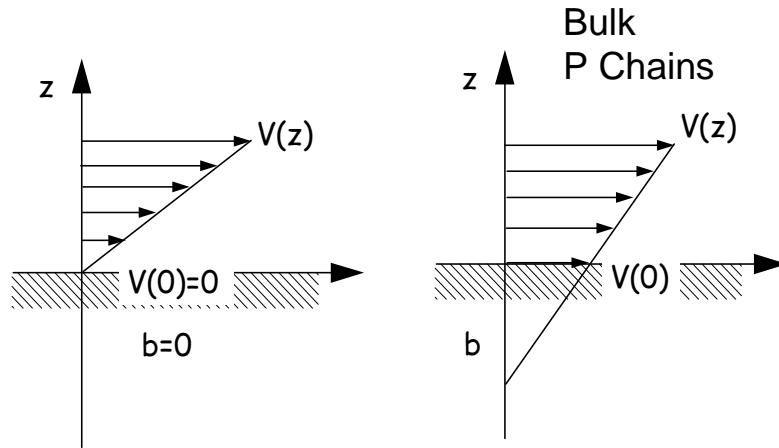
$$b = \frac{\eta}{k_{FV}}$$

Commonly admitted: $b \approx$ molecular size

Friction at polymer interfaces: interfacial slip

P. G. de Gennes C. R. Acad. Sci. Paris, 288 B, 219 (1979)

Ideal surface +
polymer melt



$$\sigma = kV(0) = \eta \left. \frac{dV}{dz} \right|_{z=0} = \eta \frac{V(0)}{b}$$

$$k = \frac{\sigma}{V(0)} \quad k \propto \frac{\eta}{b}$$

k = friction coefficient at interface

Fluid of monomers : $b = \frac{\eta_1}{k} \approx a \quad a \approx \text{few } \text{\AA}$

Polymer : $b = \frac{\eta(P)}{k} = \frac{\eta(P)}{\eta_1} a$

Polymer : $\frac{\eta(P)}{\eta_1} \approx 10^5 \text{ to } 10^6$

$b \approx 10 \text{ to } 100 \text{ } \mu\text{m}$
Huge slip

Experimental indications:

➤ Polymer melt extrusion:

J.J. Bembow, P. Lamb, SPE trans. 3, (1963), 7

A.M. Kraynik, W.R. Schowalter, J. Rheol. 25, 95 (1981)

R.H. Burton, M.J. Folkes, K.H. Narh, A. Keller, J. Mater. Sci. 18, 315 (1983)

G.V. Vinogradov, V.P. Protasov, V.E. Dreval, Rheol. Acta, 23 (1984) 46

A.V. Rammamurthy, J. rheol., 30, (1986) 337

N. El Kissi, J.M. Piau, C.R. acad. Sci. 309, 7 (1989) and J. non Newtonian Fluid Mechanics, 37, (1990) 55 – 94

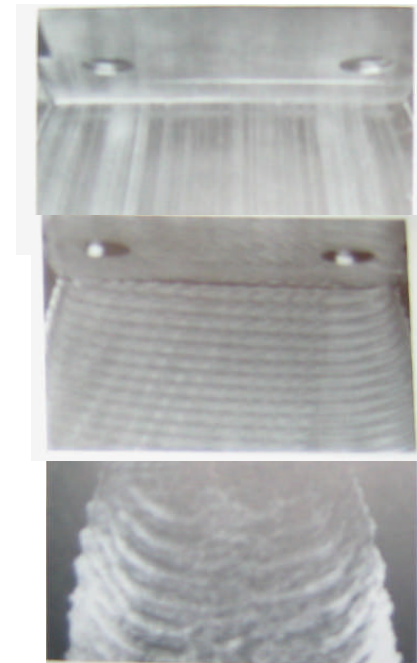
S. G. Hatzikiriakos, J.M. Delay, J. rheol. 36, 703 (1992)

.....

- Some evidences of slip (pressure drop versus flow rate and thickness dependences)
- depending on the nature of the wall
- evidences of the shear rate threshold
- relation to extrusion defects

➤ Direct characterization of the flow velocity at interface:

- tracer particles *Atwood and Schowalter, Rheol. Acta 28, 134 (1989)*
- near field laser velocimetry



Experiment: Near Field Laser Velocimetry

*Léger, Hervet, Massey, in Rheology of melt processing
J.M. Piau, J.F. Agassant Edt, Elsevier (1996)*

Polymer : (PDMS)

$$M_w = 200 \text{ to } 970 \text{ kg/mol } (M_w/M_n \approx 1.1)$$

$$P = 2700 \text{ to } 13100.$$

$$D^* = N_e^{1/2} a \quad (N_e \text{ PDMS} \approx 100)$$

Entangled

End labeled with NBD
(5% by weight)

Surface:

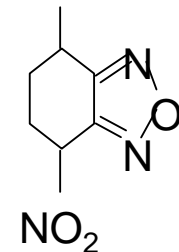
PDMS on SiO₂ (Prism)

OTS layer (ideal non adsorbing surface?)

$$\lambda_{\text{exc}} = 476 \text{ nm}$$

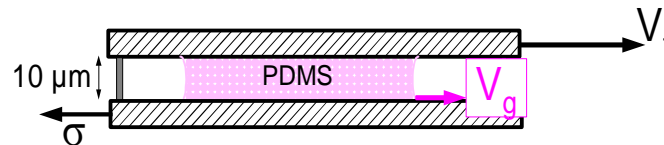
$$\Lambda_{\text{em}} = 510 \text{ nm}$$

Photobleachable



Experiment:

simple shear



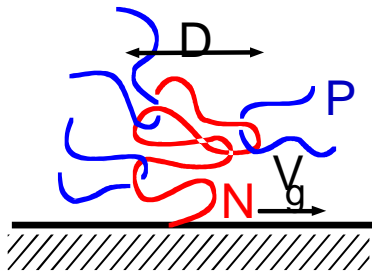
+ evanescent waves \longrightarrow sensitivity to the surface ($\Lambda \approx 50 \text{ nm}$)

K.B. Migler, H. Hervet, L.L., Phys. Rev. Lett. 70, 3, (1993) 287: 3 different slip regimes

Model: entanglements driven friction

- F. Brochard , P.G. de Gennes *Langmuir* **8** p3033 (1992): Shear dependent slippage at a polymer/solid Interface
 A. Ajdari et al *J. Phys. II France* **5** p491 (1995): Drag on a polymer chain moving in a polymer melt
 A. Ajdari, F. Brochard Wyart, P. G. de Gennes, L. Leibler, J.L. Viovy, M. Rubinstein, *Physica A* **204**, 17 (1994)
 F. Brochard et al. *Macromol.* **29** p377 (1996): slippage of polymer melts on grafted surfaces
 C. Gay, Thesis University Paris VI, 1997

- $D > D^*$: weak deformation of surface chains →



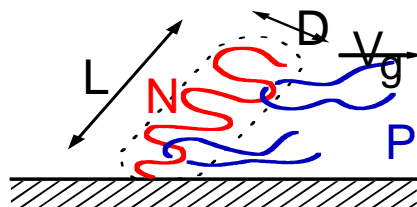
$$\sigma \propto V_S$$

$$b = \frac{\eta_p V_S}{\sigma} = \text{cte}$$

Fixed number of entanglements

Linear Friction

- $D = D^*$: marginal regime



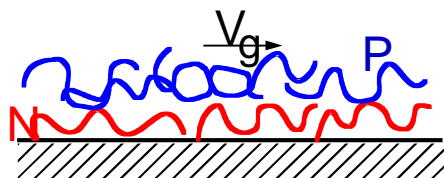
$$\dot{\gamma}^* = \sum \frac{kT}{\eta_p a^2 D^*} \propto \Sigma$$

$$V_S^* = \frac{kT}{\eta_p N a^2} \propto P^{-3.3} N^{-1}$$

$$b = \frac{V_S}{\dot{\gamma}^*}$$

Non linear Friction

- $D \ll D^*$: disentangled regime



$$\frac{V_S}{D^*} \geq \frac{1}{\tau_{rep}}$$

$$b = b_\infty \cong \frac{a \eta_p}{\eta_0}$$

$$V_S \propto \dot{\gamma}$$

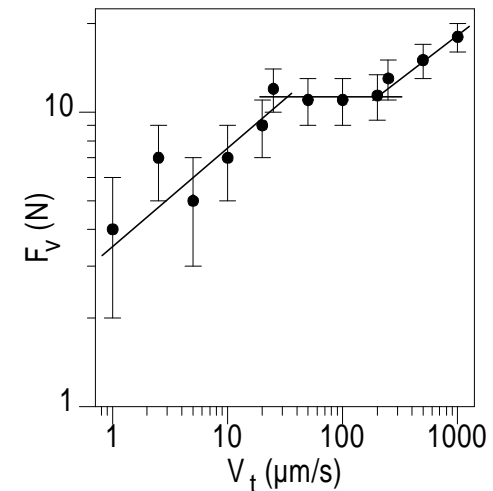
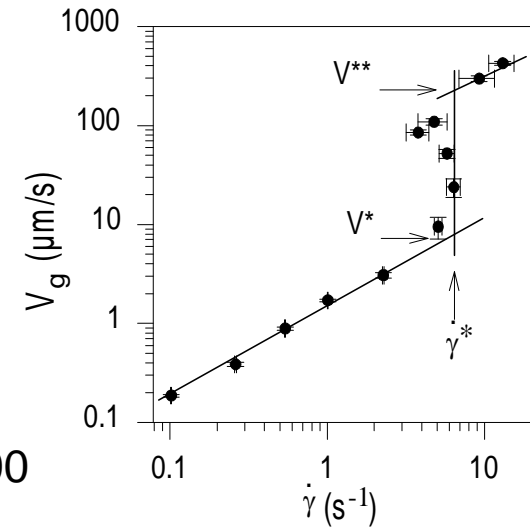
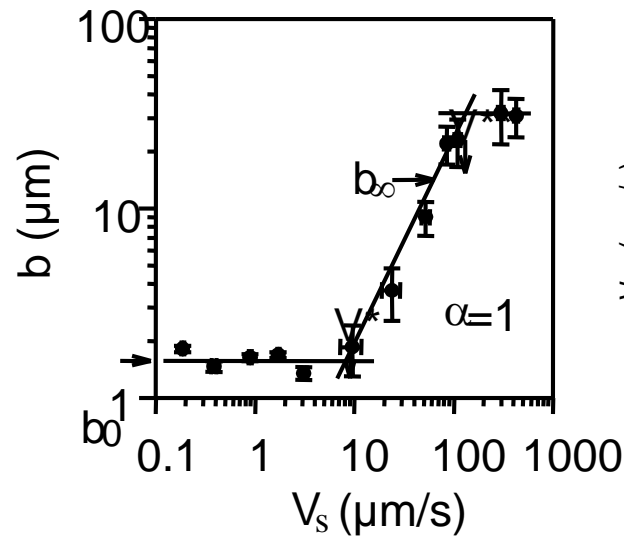
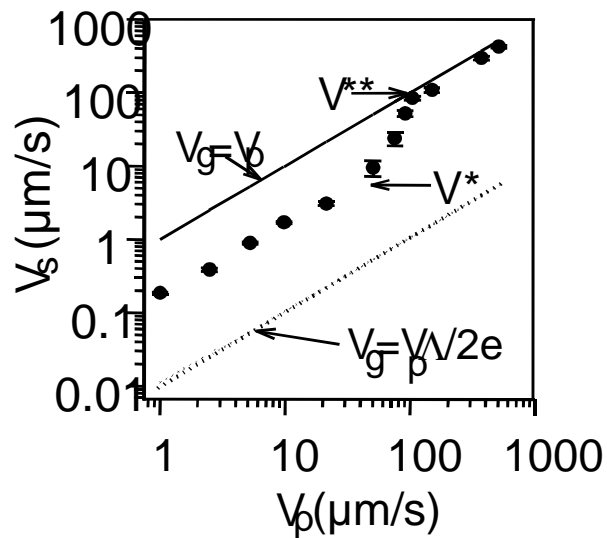
Linear, low friction

Typical results :

Bulk PDMS melt: $M_w=970$ kg/mol

Surface: silica + end grafted PDMS

$M_w=96$ kg/mol, $\Sigma=0.0055$



E. Durliat Thesis Univ. Paris VI (1997)

*E. Durliat et al. Europhys. Lett **38**, 383 (1997) and
J. Phys. Condens. Matter **9**, 7719 (1997)*

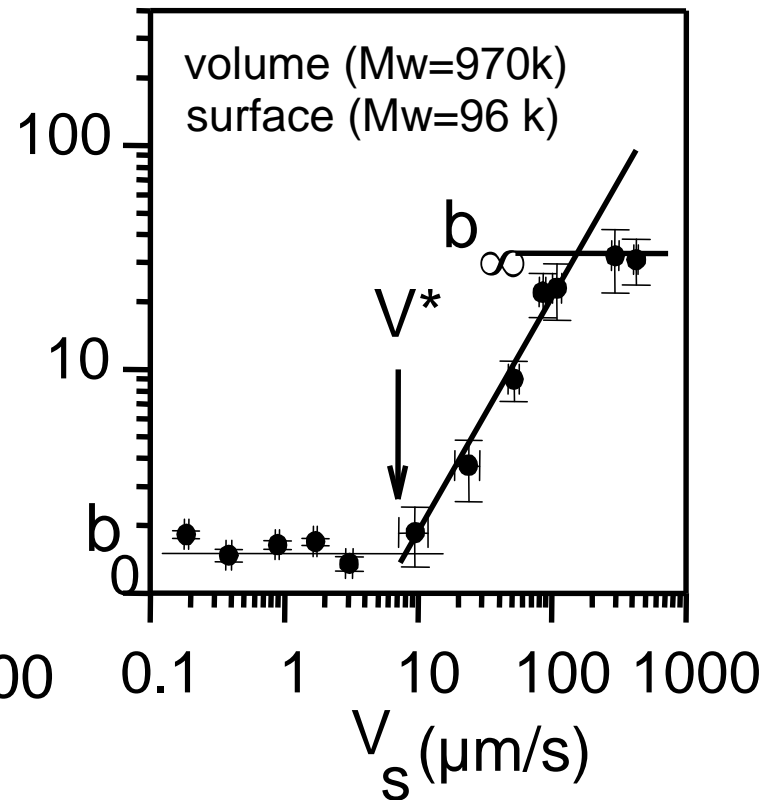
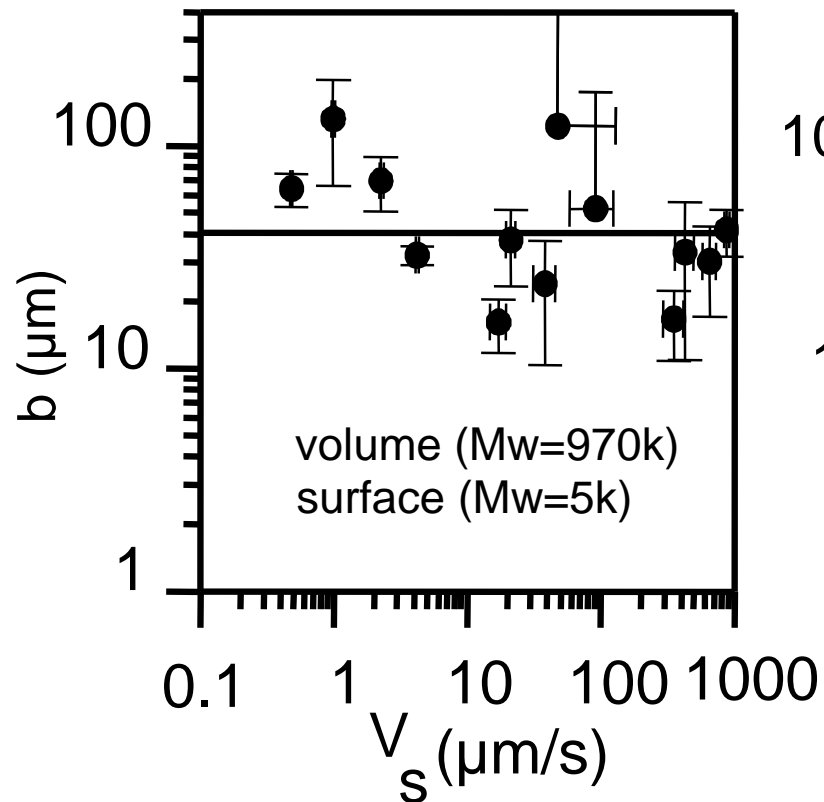
*L. Léger et al. Advances in Polymer Sci. **138**, 185
(1999)*

Entanglements driven friction

Bulk Polymer: PDMS $P > N_e$

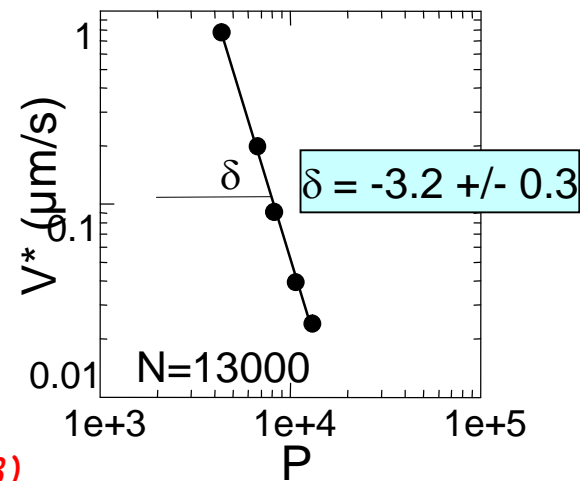
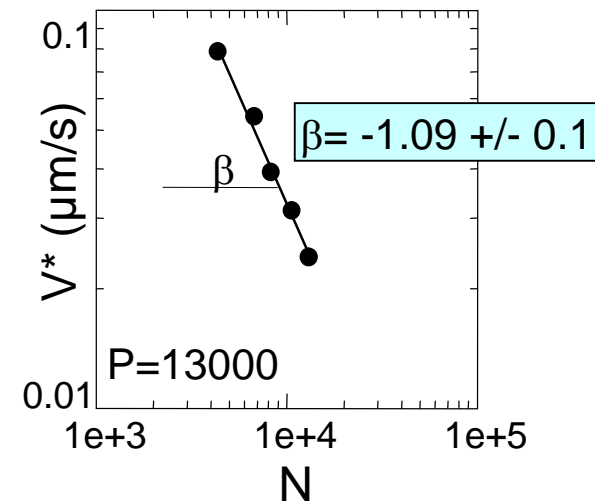
Surface: PDMS brush

Short grafted chains:
Only high slip regime



Effects of molecular weights on V^*

$$V^* = \frac{kT}{\eta_p a^2 N} \propto N^{-1} P^{-3,3}$$

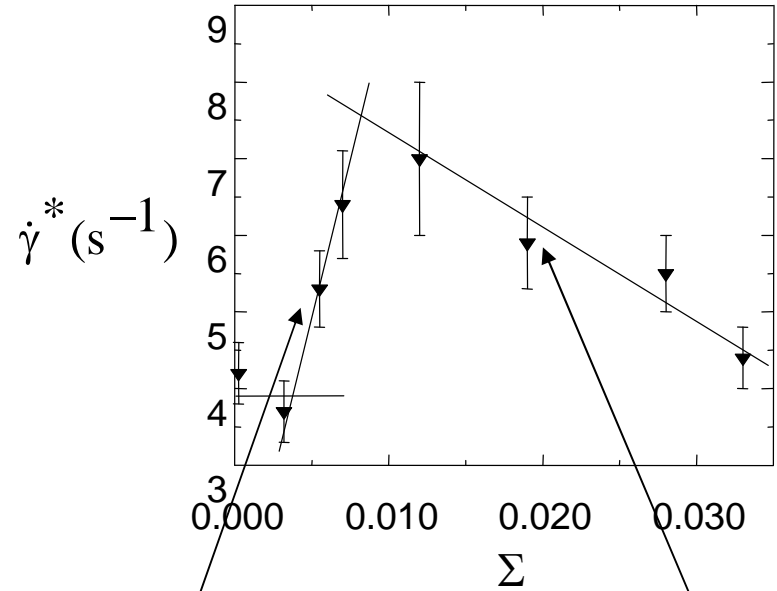


Massey G., Hervet H., Léger L. Europhys Lett 43, 83 (1998)

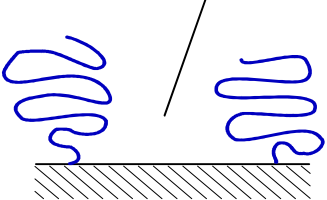
Role of the surface grafting density : Σ

M(P) = 970 kg/mole
M(N) = 96 kg/mole

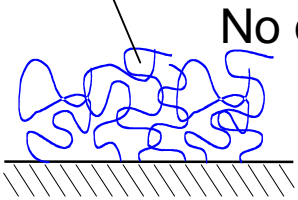
E. Durliat et al. Europhys. Lett 38, 383 (1997)



$$\dot{\gamma}^* = \frac{\Sigma kT}{a^2 D^*} \propto \Sigma$$



$$\dot{\gamma}^* \propto \Sigma$$



No quantitative predictions

Non independent surface chains :
Easier decoupling: bulk chains expelled from grafted layer
Entanglements inside the grafted layer: less defromable

- Qualitative agreement between model and experiments
- Can we do more than get a qualitative agreement?

Direct measurement of the friction force on one grafted chain,
as a function of sliding velocity

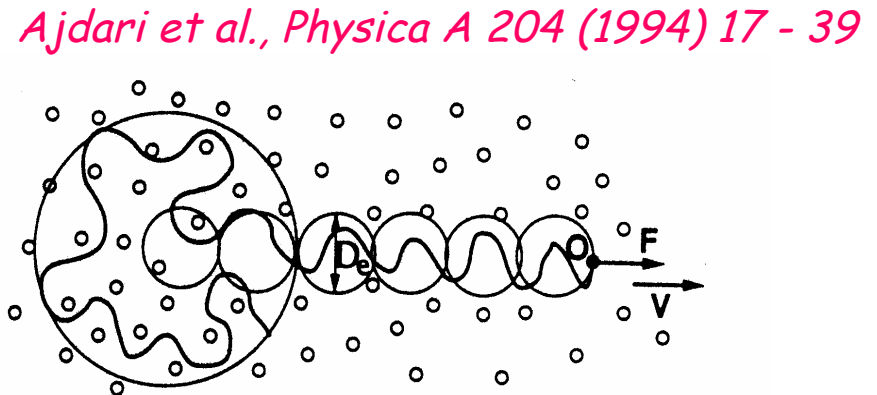
Friction force on one chain

One chain Z , pulled out of an elastomer or a melt N , under the force F

Dynamics driven by arm retraction:

$$\tau_{\text{arm}}(Z) = \tau_1 Z^2 \exp(\mu Z / N_e)$$

compare D_e/V to τ_{arm}



1) $V < V_1 = D_e / \tau_{\text{arm}}(Z)$: $F = \frac{kT}{D_e} \frac{V}{V_1}$

chain fully relaxed

2) $V_1 < V < V_2 = D_e / \tau_1 Z^2$: $F = \frac{kT}{D_e} + (Z - q)\zeta_1 V$

relaxed tail, q monomers
 $q(V)$ such that $v \tau_{\text{arm}}(q) = D_e$

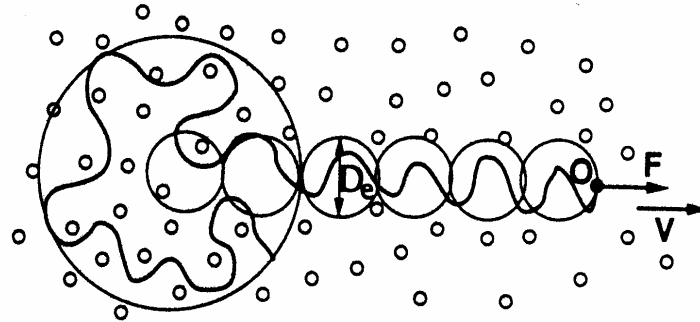
3) $V_2 < V < V_3 = V_2 (Z/N_e)^2$: $F = \frac{kT}{D_e} + (Z - q)\zeta_1 V$

Force $\approx V$ independent

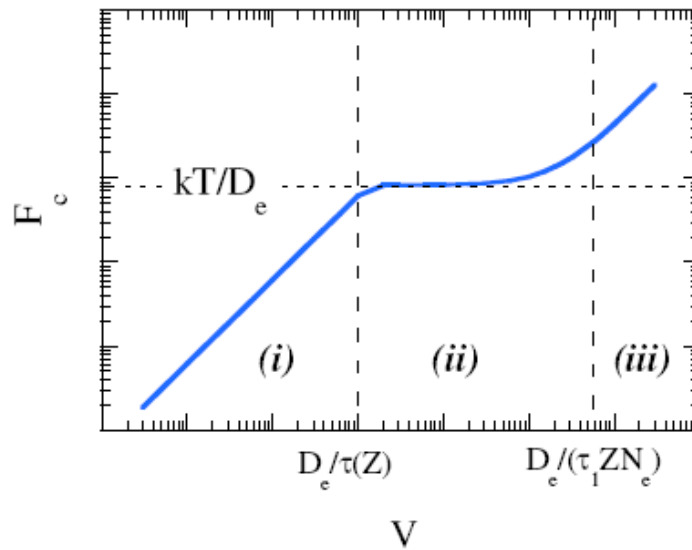
4) $V_3 < V$: $F = Z \zeta_1 V$

ζ_1 monomer friction coefficient

Pull-out friction on one chain



Compare D_e/V to $\tau \sim \tau_1 Z^2 e^{q^2/(N_e Z)}$



(i) $F_c \propto V$

(ii) $F_c = \frac{kT}{D_e} + (Z - q)\zeta_1 V$

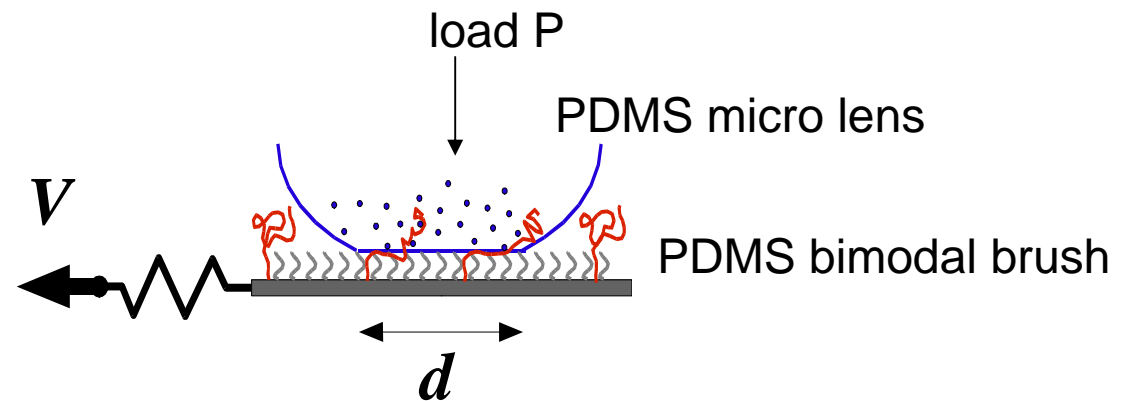
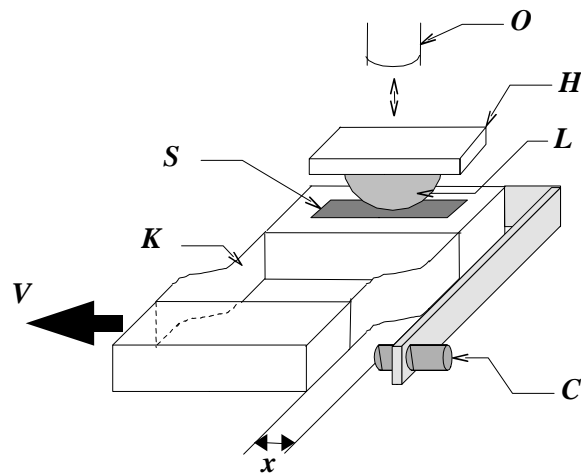
(iii) $F_c \propto V$

Experimentally $F_c = (\sigma - \sigma_{short})/\Sigma$

Direct measurements of the Friction force : Elastomer – grafted surface

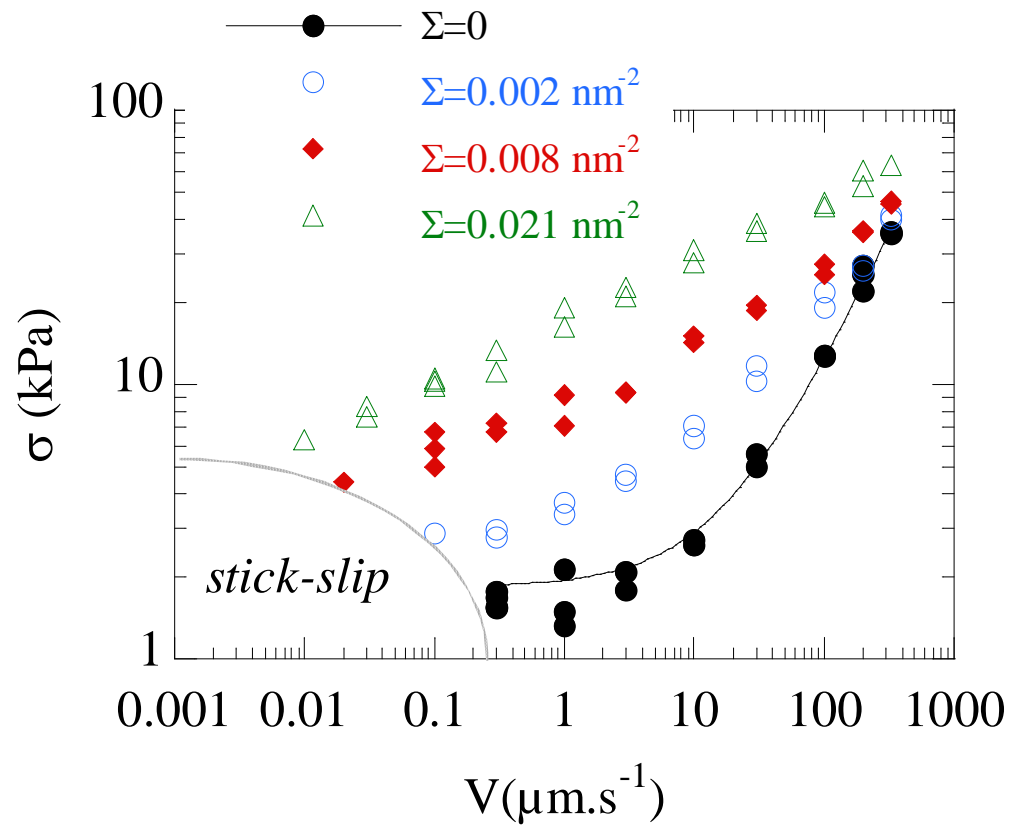
L. Bureau, L. Léger, Langmuir (2004)

- JKR like experiments (fixed contact area)
- friction force measurement: spring translated at chosen velocity



$3 \text{ nm/s} < V < 330 \text{ } \mu\text{m/s}$; $d = 200 - 400 \text{ } \mu\text{m}$; $F = 50 \text{ } \mu\text{N} - 50\text{mN}$

Results:



$$M_{\text{wlong}} = 114 \text{ kg/mole}$$

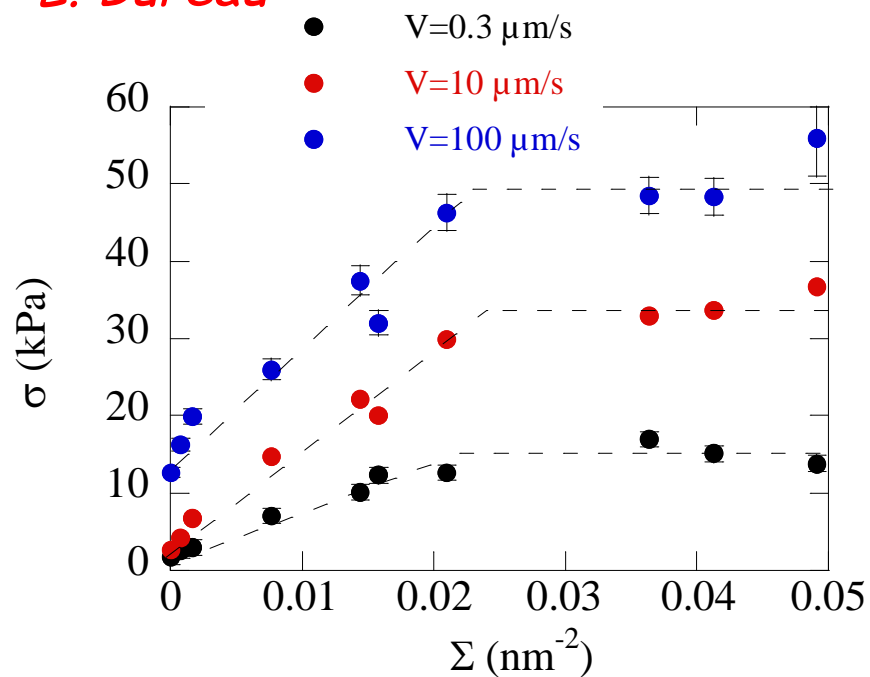
- Two regimes:
 - $V > V_c$ stationary slip motion
 - $V < V_c$ Stick-slip
- $\sigma(V)$ non linear

Effects of Surface density

Two regimes in Σ :

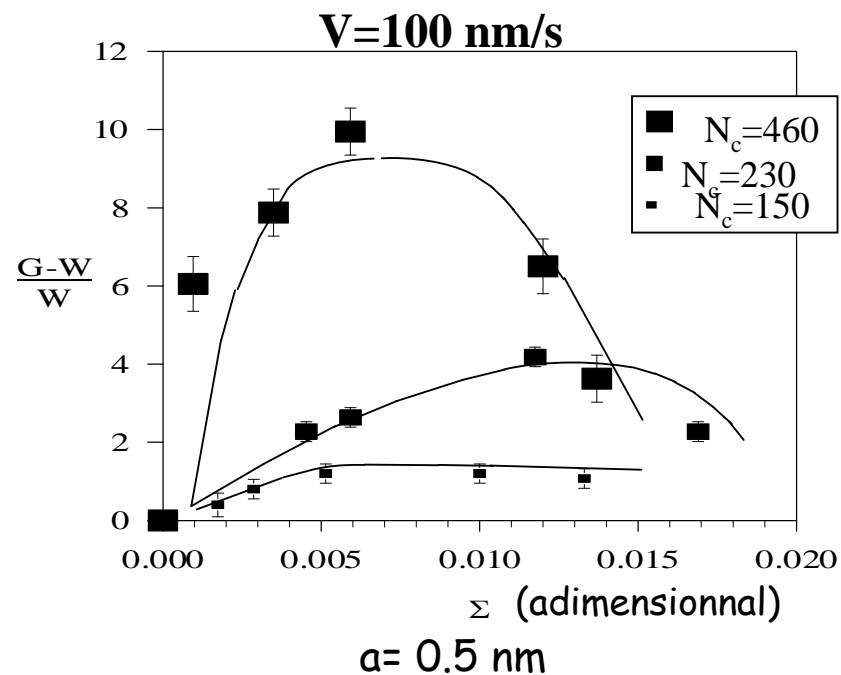
- Low Σ : σ increases linearly with Σ
- High Σ : saturation

L. Bureau



Adhesion: same systems

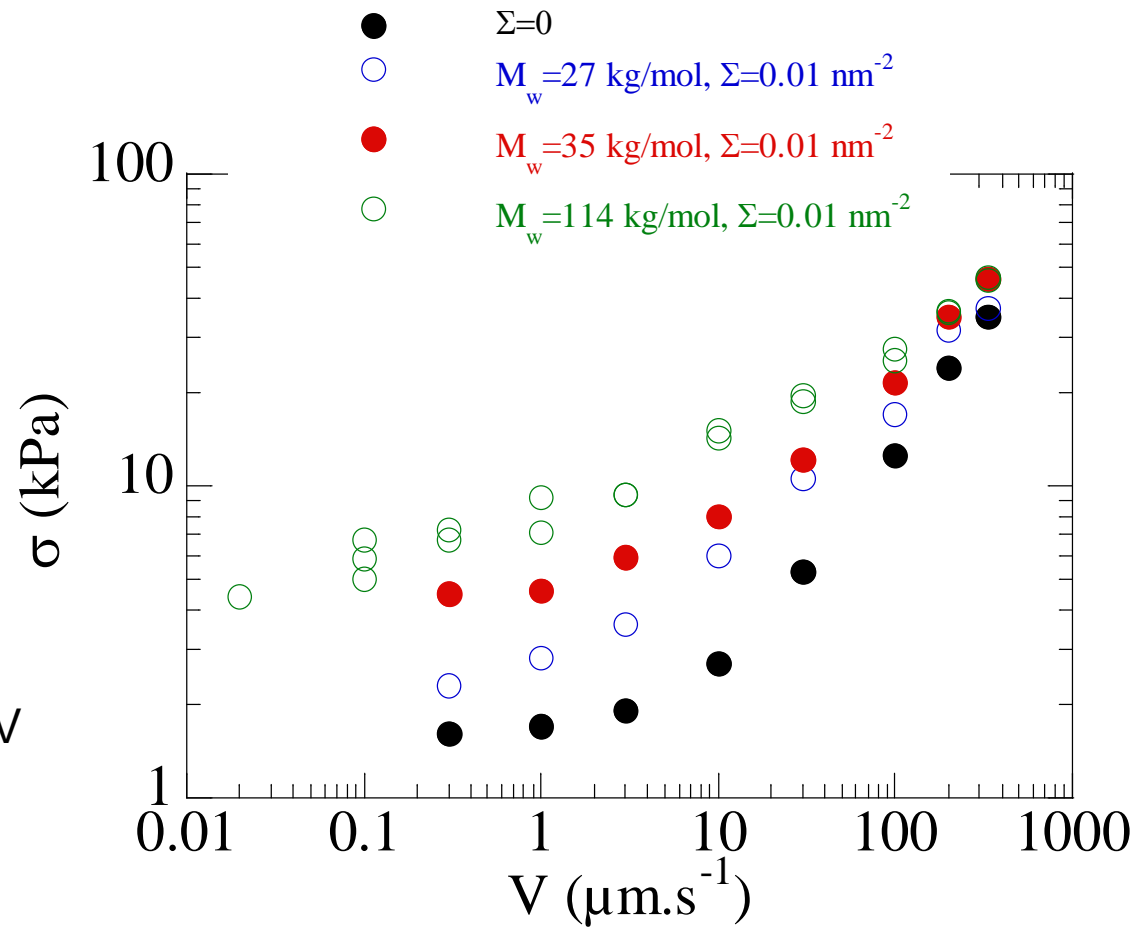
C. Tardivat



Molecular weight effects

low Σ regime:

σ increases with M at small V
curves merge at large V



Friction for $\Sigma = 0$

$$\sigma = \sigma_0 + kV$$

$$k = 10^8 \text{ Pa}\cdot\text{s}\cdot\text{m}^{-1}$$

Dense layer of short chains:
no entanglements:

monomer – monomer friction

$$\sigma = \sigma_{\text{mono}} = \zeta_1 V/a^2$$

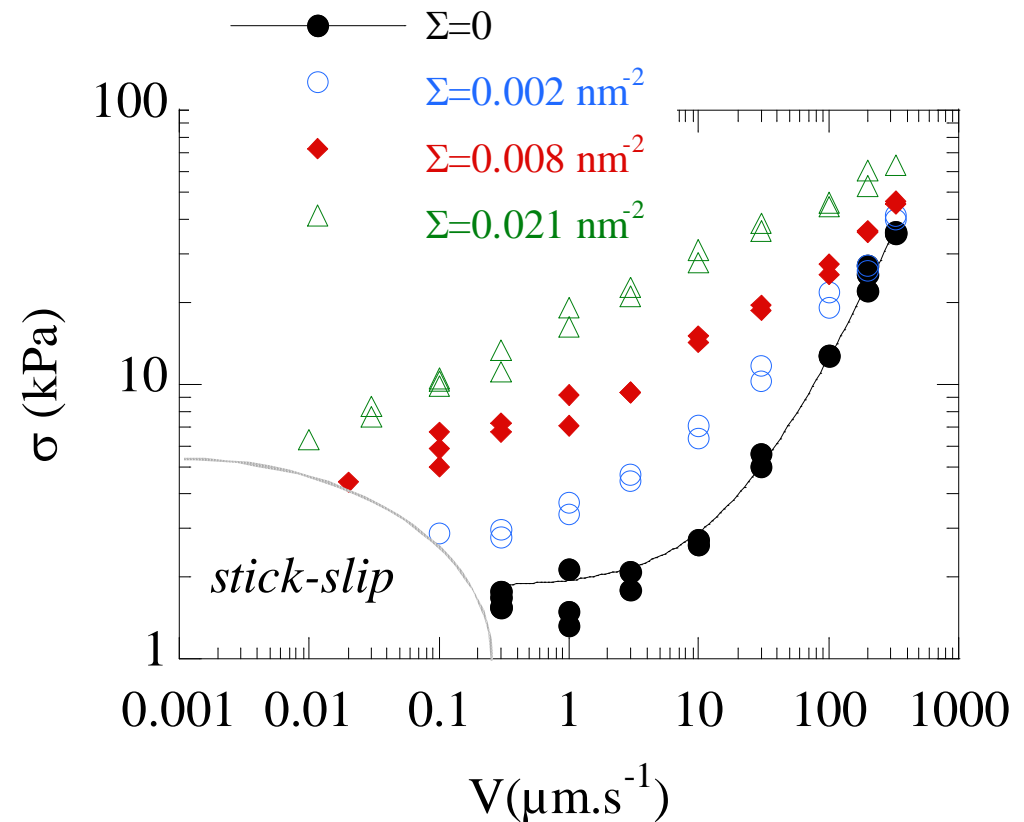
$$\zeta_1 = ka^2 = 2.5 \cdot 10^{-11} \text{ N}\cdot\text{s}\cdot\text{m}^{-1}$$

compared to

$$\zeta_1 = 10^{-11} \text{ N}\cdot\text{s}\cdot\text{m}^{-1} \text{ (self diffusion)}$$

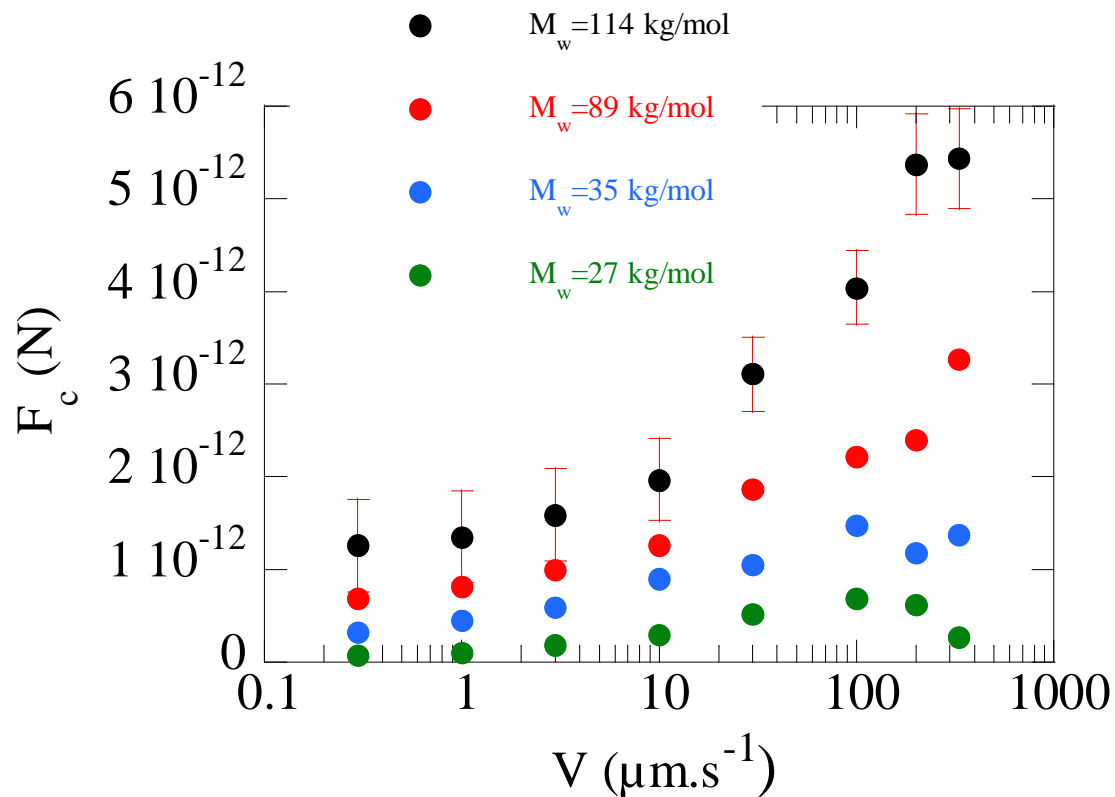


OK with monomer – monomer friction



Experiments: Friction Force on one connector F_c

$\Lambda \omega \Sigma$ regime: $\sigma(V) = \sigma_{\Sigma=0}(V) + \Sigma F_c(V)$



two different Σ for each M



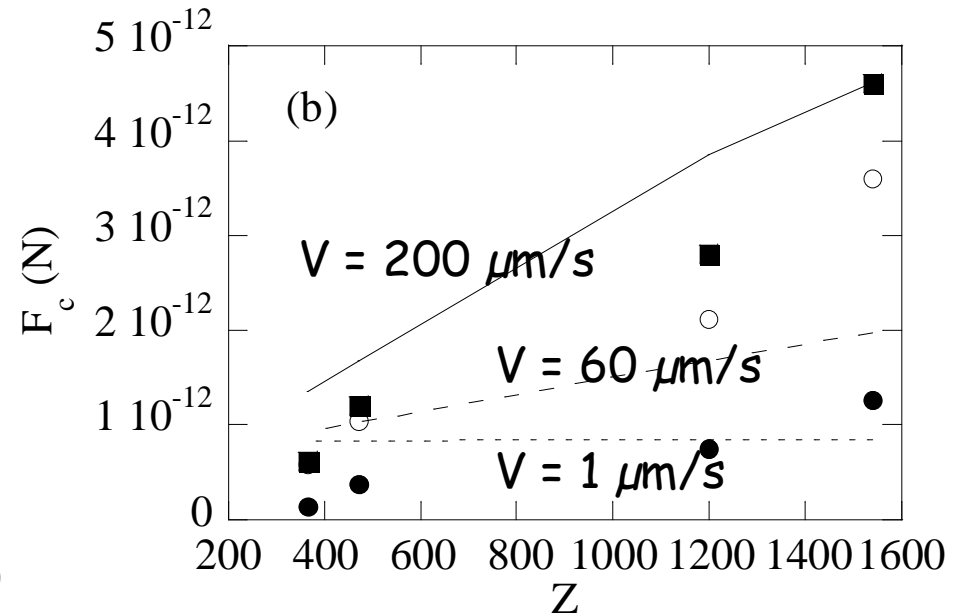
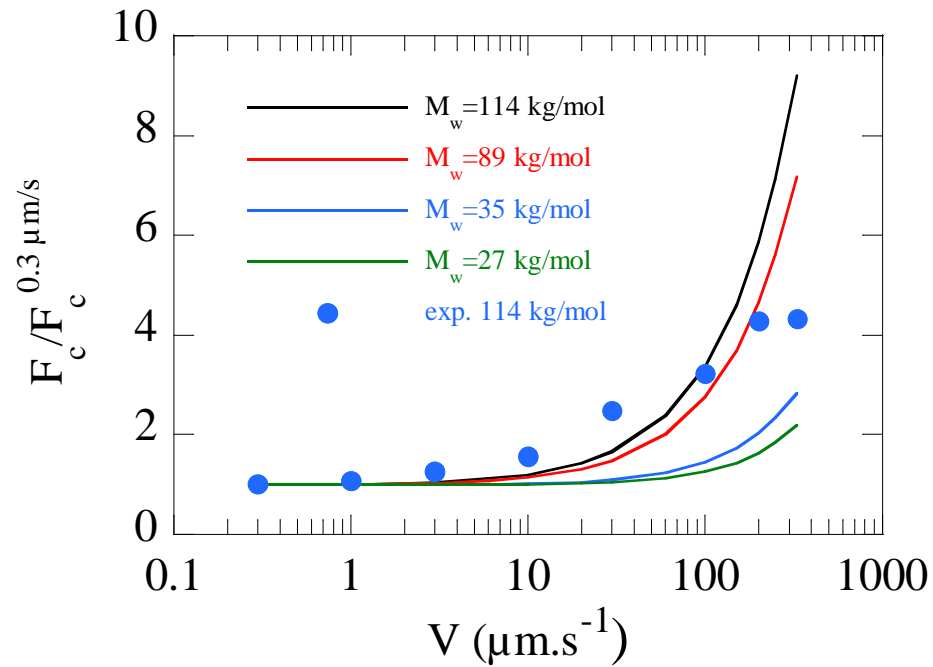
Σ independent

$$F_1 = kT/D_e \approx 8 \cdot 10^{-13} \text{N}$$

quantitative agreement
with $F_c(0, 3 \mu\text{m/s})$

Molecular weight dependence at low V ?

Comparison with Ajdari et al prediction



quantitative agreement, no adjustable parameter

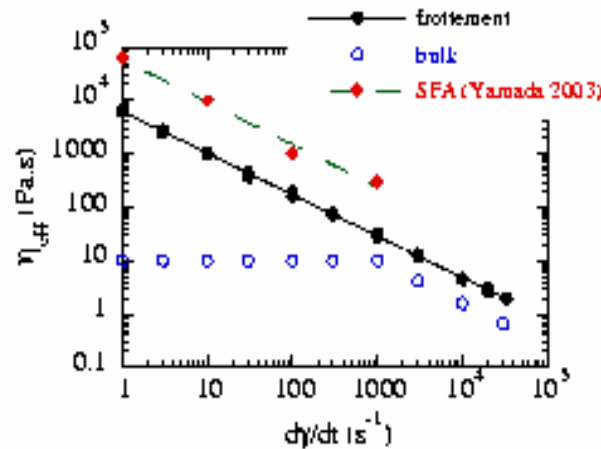
Chain pull out governs friction at low Σ

Friction mechanisms at large Σ

Chains are expelled from the elastomer at large enough Σ
(swelling elasticity of the elastomer, *P.G. de Gennes C.R. acad Sc. Paris 1994*)

$$\sigma \approx V^{0.2}$$

$$\eta_{\text{eff}} = \sigma h / V$$



Confined entangled layer of chains tethered to the surface,
thickness h , submitted to shear

$\sigma(V)$ gives access to the nano-rheology of
the confined layer of tethered chains

Friction mechanisms: what have we learn?

- Tethered polymer chains deeply affect elastomer or melt– solid friction
- As soon as interdigitation is possible, the pull out mechanism leads to non linear frictions regimes, with transitions between regimes characterized by a central regime where the friction force is independent of the velocity
- Quantitative agreement with Adjdari et al. model for independent tethered chains
- It is then possible to design surfaces with adjusted friction
- At large grafting densities, the chains form a confined layer out of the elastomer. Macroscopic friction force measurements can lead to characterization of the rheology in the confined layer

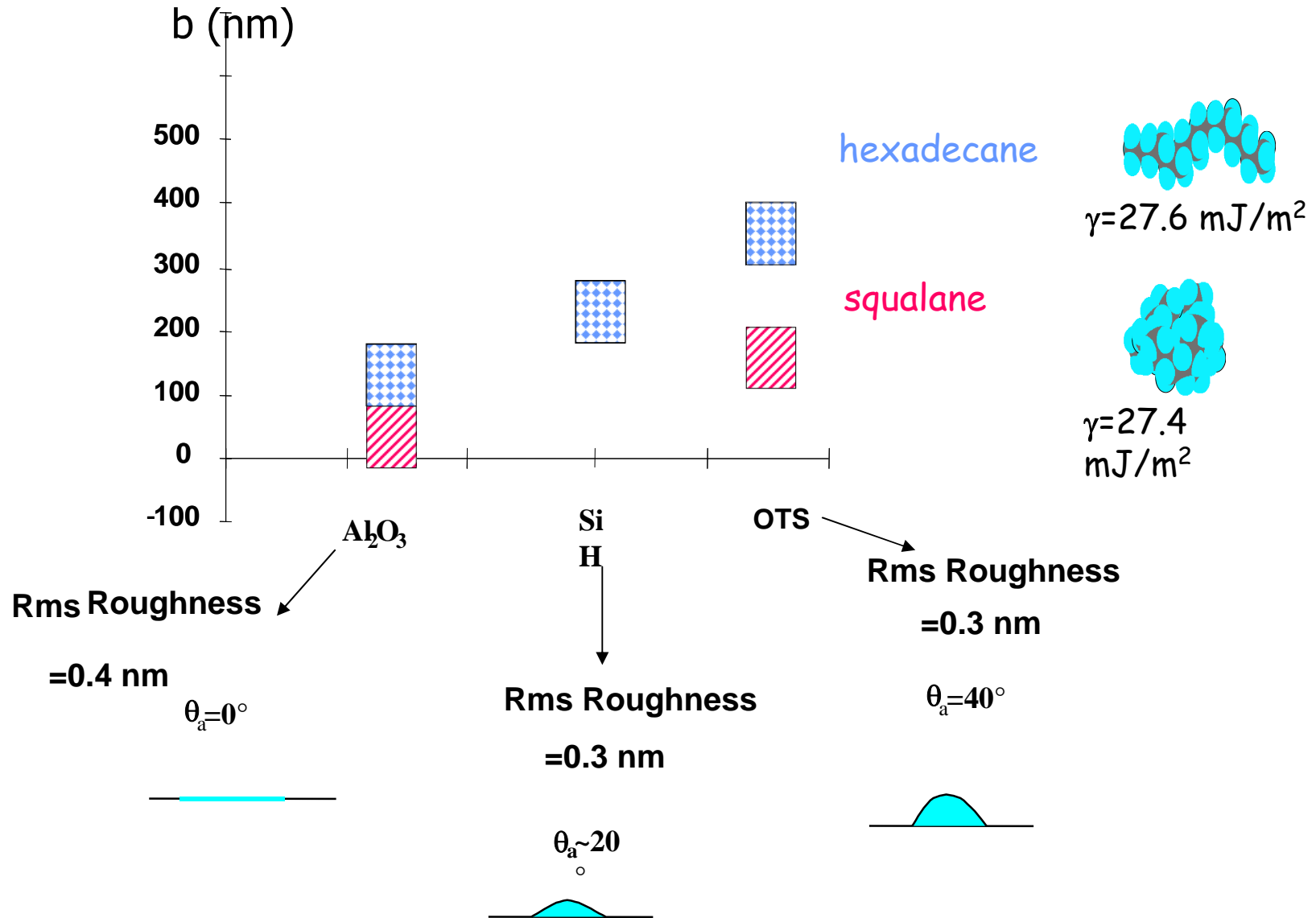
Closely related problems

- Sliding molecules at polymer/polymer interfaces: (*weakly incompatible polymers*)
F. Brochard Wyart, P.G. de Gennes, C.R. Acad. Sci. Paris, 317 serie II, 13 – 17 (1993)
- Suppressing slippage at incompatible polymer interfaces with diblock copolymers:
F. Brochard Wyart, P.G. de Gennes, P. Pincus, C.R. Acad. Sci. Paris 314 serie II, 873 – 878 (1992)
- Nanorheology of polymer melts between grafted surfaces:
F. Brochard Wyart, P.G. de Gennes, C.R. Acad. Sci. Paris, 317 serie II, 449 - 453 (1993)
- Wetting and de-wetting:
Brochard F., de Gennes P.G., J. Phys. Lett. 45, L597 (1994)
F. Brochard-Wyart, P.G. de Gennes, H. Hervet, C. Redon, Langmuir 10, (1994) 1566 – 1572
Redon C., Brochard, F. Macromolecules 27, 468 – 471 (1994)
Brochard F., Redon, C., Sykes C., A.R. Acad. Sci. Paris 314, 19 (1992)
- Correlation to adhesion behavior:
B. Z. Newby, M. Chaudhury, Langmuir 13, (1997) 1805 – 1809
H. Brown, Faraday Discuss. 98, (1994) 47 – 54; Science, 263, 1411 (1994)
- Further theoretical work:
Y. M. Joshi, A. K. Lele, J. Rheol. 46 (2002) 427: wall slip at high surface coverage
J. L. A. Dubbeldam, J. Molenaar, Phys. Rev. E 67 011803 (2003): self consistent dynamics of wall slip

Open questions

- Friction at grafted surfaces – polymer solution interfaces: shear banding?
- What happens with polyelectrolytes, with weakly associating polymers
- Melt fracture of entangled polymer melts: *P.G. de Gennes, Eur.Phys.J.E 23 3-5 (2007)*
possible explanation of discontinuities in the flow field
- What finally fixes the value of k , the friction coefficient at the surface?
experiments of near field laser velocimetry in simple fluids

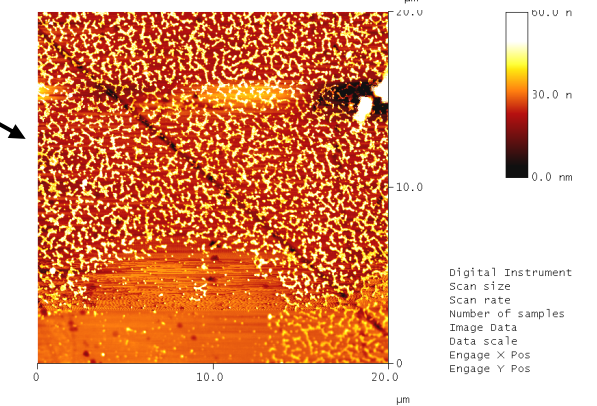
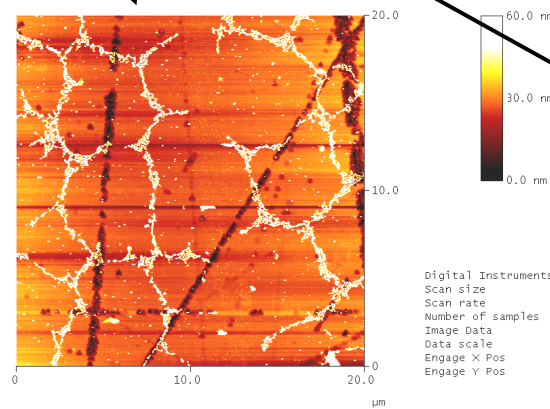
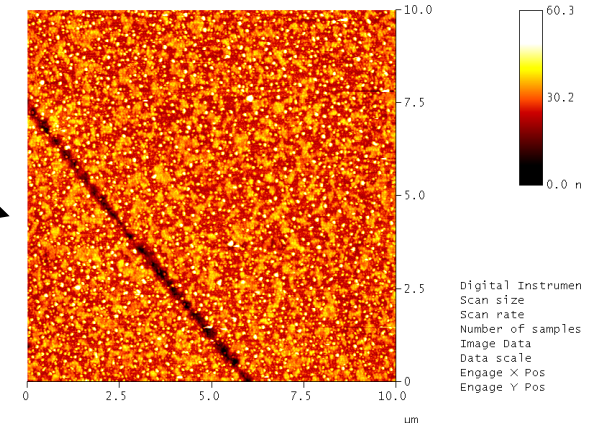
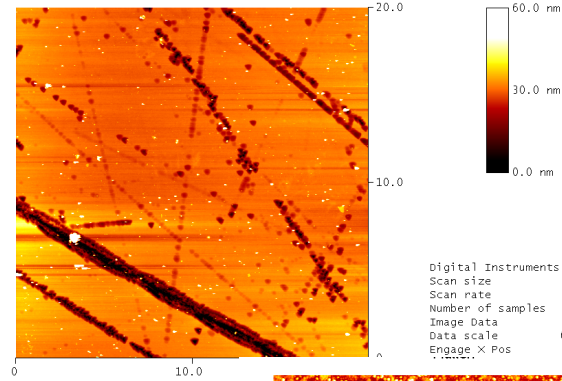
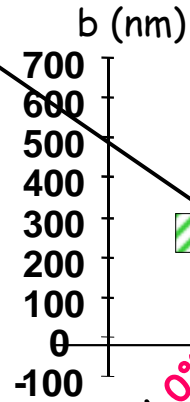
. Schmatko et al. PRL 94, 244501 (2005)



High sensitivity to nano-roughness

Rms roughness = 0.3 nm
(XR reflectivity)

hexadecane



Schmatko et al. Langmuir (2006)

